

6th Malaysia Statistics Conference 19 November 2018

Sasana Kijang, Bank Negara Malaysia

Embracing Data Science and Analytics to Strengthen Evidence-Based Decision Making

2018

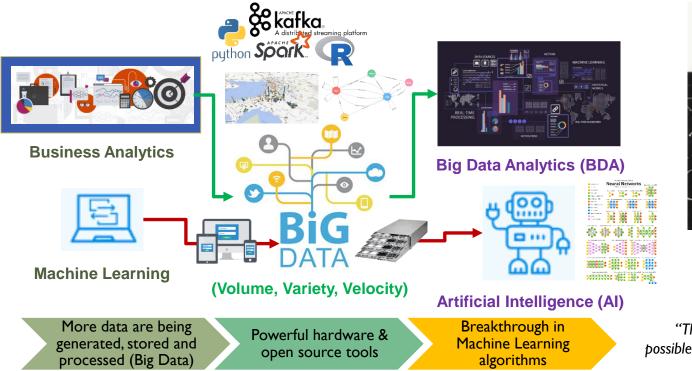
Data Science & Analytics

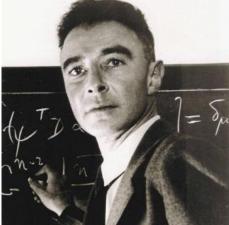
Accelerates Data Science with Automated Machine Learning

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We Are Closer





J. Robert Oppenheimer Theoretical physicist father of the atomic bomb "The optimist thinks this is the best of all possible worlds. The pessimist fears it is true."



Beginning of Artificial Intelligence (AI)

A Proposal for the Dartmouth Summer Research Project on Artificial Intelligence

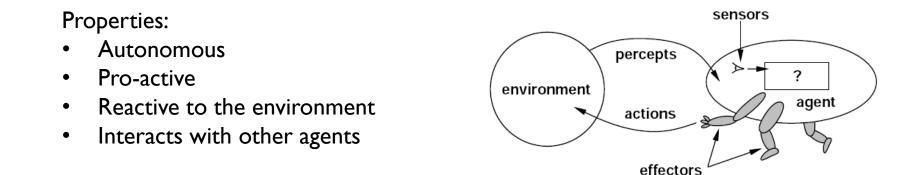
August 31, 1955

John McCarthy, Marvin L. Minsky, Nathaniel Rochester, and Claude E. Shannon "We propose that a two-month, ten man study of artificial intelligence carried out during the summer of 1956..."



What is Al

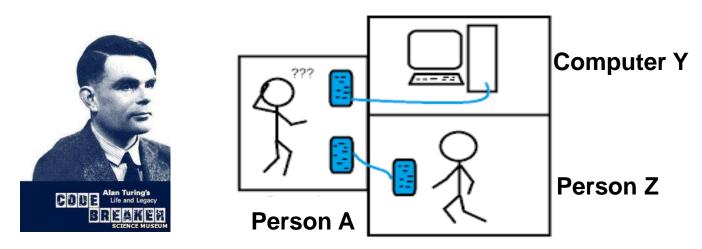
- In computer science, **Artificial intelligence** (Al, also machine intelligence) research is defined as the study of "intelligent agents".
- An intelligent agent perceives its environment via **sensors** and acts rationally upon that environment with its **effectors**.





Is AI Exists

• Alan Turing proposed a method then be known as the **Turing Test** - if the human being conducting the test is unable to consistently determine whether an answer has been given by a computer or by another human being, then the computer is considered to have intelligence.





First Wave

- The first wave of AI came in the late 1950s. It is basically a search program that based on predefined rules.
- In order for the AI to be successful, human had to precisely defined every possibility. As machine can generally process faster than human, it doesn't bother the size of pattern to search for, as well as the rules that defined how to sort and search.
- The classic example of this type of AI is how machine plays chess. For every move, a machine simply calculates massive amounts of known patterns and evaluates the best board position.
- Unfortunately, even the DeepBlue still doesn't understand concepts of the game and just rely on brute force approaches to play.
- The first winter of AI the **Frame Problem**.



Deep Blue IBM chess computer

Garry Kasparov World Chess Champion

First match

- February 10, 1996: takes place in Philadelphia, Pennsylvania
- Result: Kasparov-Deep Blue (4-2)
- Record set: First computer program to defeat a world champion in a *classical game* under tournament regulations

Second match (rematch)

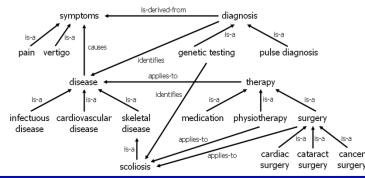
- May 11, 1997: held in New York City, New York
- Result: Deep Blue-Kasparov (31/2-21/2)
- Record set: First computer program to defeat a world champion in a *match* under tournament regulations





Second Wave

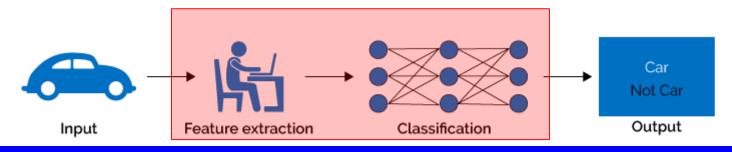
- The second wave of AI came in the 1980s. This time, its creators proposed a systematic way to representing information about the world in a form that a computer can utilize, it is called the Knowledge Representation and Reasoning.
- Effective KR requires a combination of common **vocabulary** and **automated reasoning engine**. The vocabulary, or **ontology**, provides a set of concepts and relationships between them. Unfortunately, it would requires tremendous effort to map reality into computerized vocabulary. Moreover, machines in KR are actually recognize the vocabulary and connections, not the concepts of the real world. The second winter of AI – the **Symbol Grounding Problem**.





Third Wave

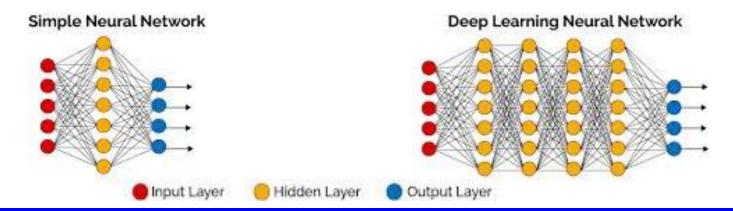
- The **third wave** of AI comes with Machine Learning (ML). Arthur Samuel in 1959 defined ML as **'giving computers the ability to learn without explicitly programmed'**. ML generally constructs a model that generated from one or more algorithms. Then, the model can be used to make predictions on new data.
- In simplified terms, every complex question can be replaced with a binary question. For example, the complex question 'Which author do you like?', can be replaced with binary questions like 'Do you like Haruki Murakami?', 'Do you like Milan Kundera?', 'Do you like Italo Calvino?'... Once in binary form, ML will suggest the best outcome from its evaluation.
- Unfortunately, a machine must at first learn correctly, before it can do prediction correctly. In all the ML before next wave, a machine by itself is not able to decide what is appropriate data and algorithm(s). The third winter of AI the Feature Engineering and Algorithm Selection Problem.





Fourth Wave

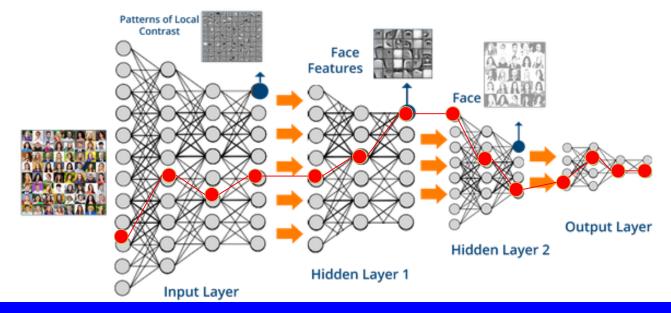
- **Deep Learning** (DL) is a new area of Machine Learning (ML) research, which has been introduced with the objective of moving ML closer to one of its original goals Artificial Intelligence (AI).
- DL means using a neural network with **multiple layers of nodes** between input and output.
- The series of layers between input & output do feature identification and processing in a series of stages, just as our brains seem to.





Deep Neural Network (DNN)

• A deep neural network (**DNN**) is an artificial neural network (**ANN**) with multiple hidden layers between the input and output layers. DNNs are typically **feedforward** networks in which data flows from the input layer to the output layer without looping back.





Deep Learning in ILSVRC 2012

• The current hype on Al is an extension of the ML, Geoffrey Hinton and his students managed to push neural network to next level, the deep neural network. In 2012, Geoffrey's SuperVision team stormed the world in ImageNet Large Scale Visual Recognition Challenge 2012 (ILSVRC2012).

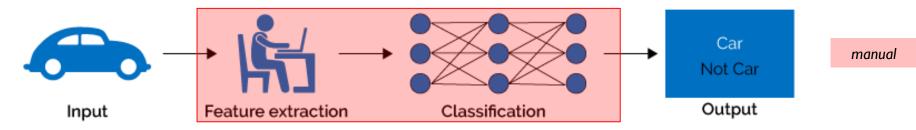


| | | | Task | | |
|---------------------------------------|-------------------------|----------------|--------------|-----------|-----|
| | Team | Classification | Localization | n Average | е |
| (Univ. of Toronto) | SuperVision | | 85% | 66% | 76% |
| (Univ. of Tokyo) | ISI | | 74% | 46% | 60% |
| (Univ. of Oxford) | OXFORD_VGG | | 73% | 50% | 61% |
| · · · · · · · · · · · · · · · · · · · | XRCE/INRIA | | 73% | N/A | N/A |
| (Xerox Europe) | University of Amsterdam | | 70% | N/A | N/A |

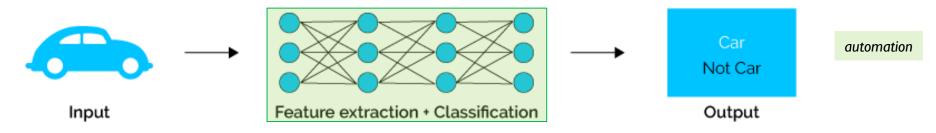


Deep Learning vs Machine Learning

Machine Learning

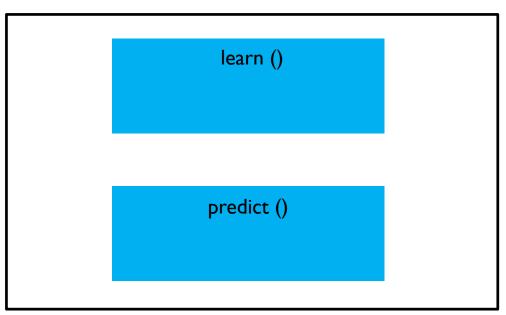


Deep Learning

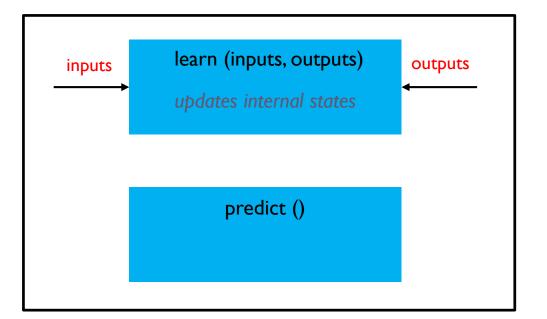




• A supervised neural network, at the abstract representation, can be presented as a black box with 2 methods **learn()** and **predict()**

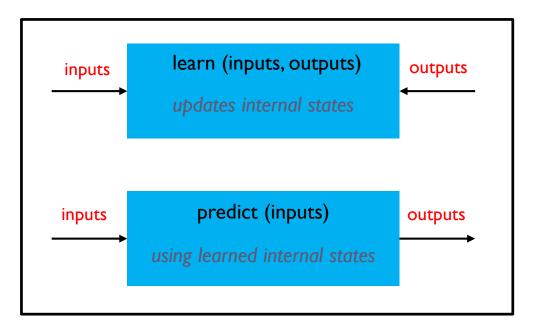






the **learning** process takes the inputs and the desired outputs and updates its internal state accordingly, so the calculated output get as close as possible to the desired output





the **predict** process takes input and using the learned internal state, to generate the most likely output according to its past *"learning experience"*



A Simple Example

- The example start with one input and one output and a linear relation between them.
- The goal of the supervised neural network is to try to search over all the possible linear functions which one best fits the data.
- For example, y = Wx
 (output = weight * input)

| Input | Outpu | Jt |
|-------|-------|----|
| | 0 | 0 |
| | I | 2 |
| | 2 | 4 |
| | 3 | 6 |
| | 4 | 8 |
| | 5 | 10 |



Learning process **Step I - Model initialization**:

- A **random initialization** of the model is a common practice. The rational behind is that from wherever we start, if we are perseverant enough and through an iterative learning process, we can reach the pseudo-ideal model.
- Let's consider the following random initializations:
 - (Model I): y=3x. The number 3 is generated at random.
 - (Model 2): y=5x. The number 5 is generated at random.
- We will explore later, how, through the learning process, all of these models can converge to the ideal solution (y=2x) (which we are trying to find).



Learning process Step 2 - Forward propagate:

- The next step is to check performance of random initialized model.
- Start from the input, pass them through the network layer and calculate the actual output of the model.
- This step is called forward-propagation, because the calculation flow is going in the natural forward direction from the input -> through the supervised neural network -> to the output.

| Input | | Actual output of model I (y= 3x) |
|-------|---|-------------------------------------|
| | 0 | 0 |
| | Ι | 3 |
| | 2 | 6 |
| | 3 | 9 |
| | 4 | 12 |
| | 5 | 15 |



Learning process Step 3 - Loss function:

- Defined a **loss function**, which is a performance metric on how well the algorithm manages to reach its goal of generating outputs as close as possible to the desired outputs.
- The most intuitive loss function is simply loss = (desired output-actual output). This loss function returns positive values when the network undershoot (prediction < desired output), and negative values when the network overshoot (prediction > desired output).
- If we want the loss function to reflect an **absolute** error, regardless if it's overshooting or undershooting we can define it as: loss = absolute value of (desired—actual).

| Input | | Actual output of model I (y= 3x) | Desired output | Absolute error | |
|-------|---|-------------------------------------------|-------------------|-------------------|--|
| | 0 | 0 | 0 | 0 | |
| | Ι | 3 | 2 | I | |
| | 2 | 6 | 4 | 2 | |
| | 3 | 9 | 6 | 3 | |
| | 4 | 12 | 8 | 4 | |
| | 5 | 15 | 10 | 5 | |



Learning process Step 3 - Loss function:

- Several situations can lead to the same total sum of errors. For instance, lot of small errors or few big errors.
- We would like the prediction to work under **any** situation, it is more preferable to have a distribution of lot of small errors, rather than a few big ones.
- Hence, we define the loss function to be the sum of squares of the absolute errors.

| Input | Actual output of model I (y= 3x) | Desired output | Absolute error | Square of absolute error | |
|-------|-------------------------------------------|-------------------|-------------------|-----------------------------------|--|
| 0 | 0 | 0 | 0 | 0 | |
| I | 3 | 2 | I | I. | |
| 2 | 6 | 4 | 2 | 4 | |
| 3 | 9 | 6 | 3 | 9 | |
| 4 | 12 | 8 | 4 | 16 | |
| 5 | 15 | 10 | 5 | 25 | |
| | | | | Total 55 | |

In short, the machine learning goal becomes to **minimize the loss function** (to reach as close as possible to 0).



Learning process Step 4 - Differentiation:

- Goal is to **minimize the loss function**.
- **Differentiation** in mathematics can guide us how to optimize the weights.
- Imagine, how much the total error will change if the internal weight changed!
- Let's consider $\Delta W=0.0001$. (In reality it should be much smaller!)
- Let's recalculate the **sum of squares** of the absolute errors.

| Input | | Actual output of model I (y= 3.0001x) | Desired output | abso | Square of absolute error | |
|-------|---|------------------------------------------------|-------------------|-------|--------------------------------|--|
| | 0 | 0 | | 0 | 0 | |
| | Ι | 3.0001 | | 2 | 1.0002 | |
| | 2 | 6.0002 | | 4 | 4.0008 | |
| | 3 | 9.0003 | | 6 | 9.0018 | |
| | 4 | 12.0004 | | 8 | 16.0032 | |
| | 5 | 15.0005 | I | 0 | 25.0050 | |
| | | | | Total | 55.0110 | |



Learning process Step 4 - Differentiation:

- If we increase W from 3 to 3.0001, the sum of squares of error will increase from 55 to 55.0110.
- What is the rate of which the error changes **relatively** to the changes on the weight?
- The rate is **increase** by 0.0110 in the total error for each 0.0001 increase in weight.

| Input | | Actual output of model I (y= 3.0001x) | Desired output | Squ erro | |
|-------|---|------------------------------------------------|-------------------|-------------|---------|
| | 0 | 0 | | 0 | 0 |
| | Ι | 3.0001 | | 2 | 1.0002 |
| | 2 | 6.0002 | | 4 | 4.0008 |
| | 3 | 9.0003 | | 6 | 9.0018 |
| | 4 | 12.0004 | | 8 | 16.0032 |
| | 5 | 15.0005 | I | 0 | 25.0050 |
| | | | | Total | 55.0110 |



Learning process Step 4 - Differentiation:

- If we decrease the weights by 0.0001, the sum of squares of error will decrease from 55 to 54.98900055.
- The rate is **decrease** by 0.0110 in the total error for each 0.0001 decrease in weight.

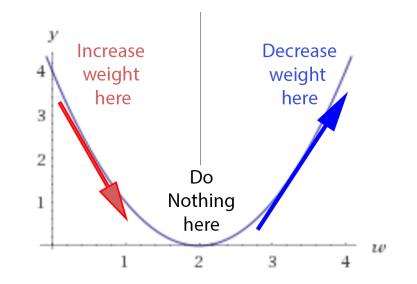
| Input | | Actual output of model I (y= 2.9999x) | Desired output | Square error |
|-------|---|------------------------------------------------|-------------------|-----------------|
| | 0 | 0 | 0 | 0 |
| | Ι | 2.9999 | 2 | 0.99980001 |
| | 2 | 5.9998 | 4 | 3.99920004 |
| | 3 | 8.9997 | 6 | 8.99820009 |
| | 4 | 11.9996 | 8 | 15.99680016 |
| | 5 | 14.9995 | 10 | 24.99500025 |
| | | | Tota | l 54.98900055 |





Learning process Step 4 - Differentiation:

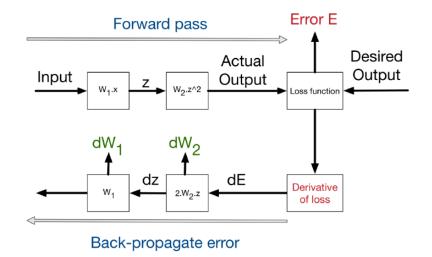
- Let's check the derivative, the rate at which error changes relatively to the changes on the weight.
- If W is < desired W, we have a positive loss function, but the derivative is negative, meaning that an increase of weight will decrease the loss function.
- If W is > desired W, we have a positive loss function, but the derivative is as well positive, meaning that any more increase in the weight, will increase the losses even more!
- If W is equal to desired W, we do nothing, we reach our stable point.





Learning process Step 5- Back-propagation:

- A more complex problem say layer I is doing 3x to generate a hidden output z, layer 2 is doing z² to generate the final output.
- In order to solve the problem, luckily for us, derivative is **decomposable**, thus can be back-propagated.
- The process of back-propagating errors: Input -> Forward calls -> Loss function -> derivative -> back-propagation of errors.







Learning process Step 6-Weight Update:

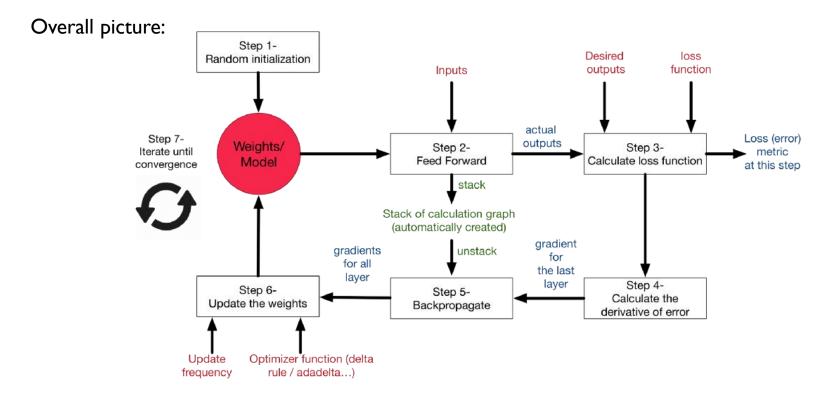
- A general rule of weight updates is the delta rule.
 new weight = old weight—Derivative Rate * learning rate
- The **learning rate** is introduced as a constant (usually very small), in order to force the weight to get updated very smoothly and slowly (to avoid big steps and chaotic behavior).
- If the derivative rate is positive, it means that an increase in weight will increase the error, thus the new weight should be smaller.
- If the derivative rate is negative, it means that an increase in weight will decrease the error, thus we need to increase the weights.
- If the derivative is 0, it means that we are in a stable minimum. Thus, no update on the weights is needed -> we reached a stable state.



Learning process **Step 7- Iterate Until Convergence**:

- A general rule of weight updates is the delta rule.
 new weight = old weight—Derivative Rate * learning rate
- The **learning rate** is introduced as a constant (usually very small), in order to force the weight to get updated very smoothly and slowly (to avoid big steps and chaotic behavior).
- If the derivative rate is positive, it means that an increase in weight will increase the error, thus the new weight should be smaller.
- If the derivative rate is negative, it means that an increase in weight will decrease the error, thus we need to increase the weights.
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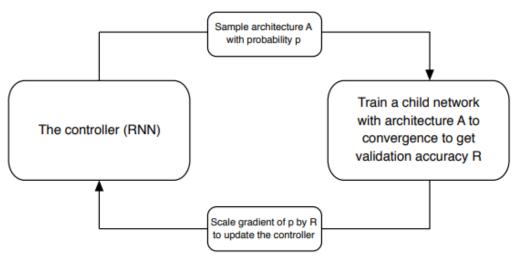


Automated ML: Neural Architecture Search (NAS)

- Developing neural network models requires specialized skills and is challenging in general.
- NAS is an algorithm that searches for the **best neural network architecture**:
 - Start off by defining a set of "building blocks" that can possibly be used for our network.
 - A controller Recurrent Neural Network (RNN) samples these building blocks, putting them together to create some kind of end-to-end architecture.
 - This new network architecture is then trained to convergence to obtain some accuracy on a heldout validation set.
 - The resulting accuracies are used to update the controller so that the controller will generate better architectures over time, perhaps by selecting better blocks or making better connections.
 - The controller weights are updated with policy gradient.



Automated ML: Neural Architecture Search (NAS)



Overview of Neural Architecture Search [71]. A controller RNN predicts architecture A from a search space with probability p. A child network with architecture A is trained to convergence achieving accuracy R. Scale the gradients of p by R to update the RNN controller.



Automated ML: Advances in Architecture Search

- NAS was quite inefficient and inaccessible to the common user. Using 450 GPUs it took 3–4 days of training to find that great architecture!
- Much of the latest research in NAS has thus focused on make this process more efficient.
- <u>Progressive Neural Architecture Search (PNAS)</u> proposes to use what is called a sequential model-based optimization (SMBO) strategy, rather than the reinforcement learning used in NASNet. This method of PNAS is 5–8 times more efficient (and thus much less expensive) than the original NAS.
- <u>Efficient Neural Architecture Search (ENAS)</u> is another shot at trying to make the general architecture search more efficient. The ENAS algorithm forces all models to share weights instead of training from scratch to convergence. Thus, we're essentially doing a transfer learning each time we train a new model, converging much faster! ENAS completed half a day of training with a single 1080Ti GPU!



Automated Machine Learning

- Google recently offering <u>Cloud AutoML</u>. Just upload your data and Google's NAS algorithm will find you an architecture, quick and easy!
- <u>AutoKeras</u> is an open source software library for automated machine learning.
- <u>DataRobot's</u> AutoML able to automate many of the tasks needed to develop artificial intelligence (AI) and machine learning applications.
- <u>H2O</u>'s AutoML can be used for automating the machine learning workflow, which includes automatic training and tuning of many models within a user-specified time-limit.
- <u>R</u>'s AutoML package fits from simple regression to highly customizable deep neural networks either with gradient descent or metaheuristic, using automatic hyper parameters tuning and custom cost function.
- <u>Python</u>'s AutoML library automated machine learning for production and analytics.
- <u>Auto-sklearn</u> is an automated machine learning toolkit and a drop-in replacement for a scikitlearn estimator.



Thank You



Setup Parse

| PARSE CONFIC | JURATION |
|----------------|-----------------------------------------------------|
| Sources | ♣ X_train.csv |
| ID | Key_Frame_X_train1.hex |
| Parser | CSV 🗸 |
| Separator | |
| Column Headers | C Auto |
| | Irist row contains column names |
| | First row contains data |
| Options | Enable single quotes as a field quotation character |
| | ☑ Delete on done |
| | |

EDIT COLUMN NAMES AND TYPES

Search by column name...

| 1 | atm_type | Enum 💌 | 0.0 | 0.0 | 0.0 | 0.0 |
|---|-------------|-----------|---------------------|---------------------|-------------------|---------------------|
| 2 | branch_name | Enum 👻 | 127.0 | 127.0 | 127.0 | 127.0 |
| 3 | is_weekend | Enum 👻 | 0.0 | 0.0 | 0.0 | 1.0 |
| 4 | last_reload | Numeric 👻 | 0.920579633271809 | 0.920579633271809 | 0.920579633271809 | 0.920579633271809 |
| 5 | last_reload | Numeric 👻 | -1.1891177907825474 | -1.0697977496481363 | -1.0 | -0.9504777085137253 |



🚠 Run AutoML

| Project Name: | atm-pred | | | |
|--------------------|----------------------------------------------|-------------|--|--|
| Training Frame: | Key_Frame_X_train.hex | | | |
| Response Column: | out_of_cash 🗸 | | | |
| Fold Column: | (Select) 👻 | | | |
| Weights Column: | (Select) 👻 | | | |
| Ignored Columns | Search | | | |
| | Showing page 1 of 1. | | | |
| | 🗖 lat | REAL | | |
| | 🔲 lon | REAL | | |
| | p2d_total_error_txn | REAL | | |
| | p2d_total_wd_amt | REAL | | |
| | p2d_total_wd_amt_since_last_reload | REAL | | |
| | p7d_total_wd_amt_since_last_reload | REAL | | |
| | term_id | ENUM(22880) | | |
| | txn_dow | ENUM(48976) | | |
| | txn.wom | ENUM(38387) | | |
| | All None | | | |
| | Only show columns with more than 0 % missing | values. | | |
| Validation Frame: | Key_FrameX_val.hex | ▼ | | |
| Leaderboard Frame: | (Select) | • | | |
| Balance classes: | | | | |



n Job

 Run Time
 02:00:03.90

 Remaining Time
 00:00:00.0

 Type
 Auto Model

 Key
 Q atm-pred

 Description
 AutoML build

 Status
 DONE

 Progress
 100%

 Done.

 Actions
 Q View



E Leaderboard

C Monitor Live

MODELS

models sorted in order of AUC, best first

| | model_id | auc | logloss | mean_per_class_error | rmse | mse |
|----|---------------------------------------------|--------------------|--------------------|----------------------|---------------------|---------------------|
| Θ | GBM_grid_0_AutoML_20181113_120203_model_203 | 0.5073806953900392 | 10.923929023622673 | 0.43484550436215463 | 0.7248732213641473 | 0.5254411870508361 |
| 1 | DeepLearning_0_AutoML_20181113_120203 | 0.5093358411996883 | 4.200541759876456 | 0.49060827468162016 | 0.9719648644559118 | 0.9447156977367991 |
| 2 | GBM_grid_0_AutoML_20181113_120203_model_22 | 0.655638867244881 | 3.117759938124701 | 0.3308946568395775 | 0.6236795709017424 | 0.3889762071601815 |
| з | GBM_grid_0_AutoML_20181113_120203_model_112 | 0.7509077177564603 | 0.6923613534615316 | 0.42931217826714524 | 0.4952430246110214 | 0.2452656534258727 |
| 4 | GBM_grid_0_AutoML_20181113_120203_model_152 | 0.7661281566543615 | 0.5875090967587011 | 0.39587910508769014 | 0.37753723130834616 | 0.14253436102397166 |
| 5 | GBM_grid_0_AutoML_20181113_120203_model_9 | 0.7668690203993 | 0.7058830392916294 | 0.30092560067444146 | 0.5063186183162819 | 0.2563585432537087 |
| 6 | GBM_grid_0_AutoML_20181113_120203_model_25 | 0.76881857779708 | 0.3154900866750758 | 0.3965121923180094 | 0.310038317557286 | 0.0961237583537525 |
| 7 | GLM_grid_0_AutoML_20181113_120203_model_0 | 0.7725412584464854 | 0.2774076647961704 | 0.40100926718356816 | 0.2634831036852671 | 0.06942334592762123 |
| 8 | GBM_grid_0_AutoML_20181113_120203_model_154 | 0.7777895755361682 | 0.5238245426238078 | 0.41311616232580123 | 0.38614071520705096 | 0.14910465194061281 |
| 9 | GBM_grid_0_AutoML_20181113_120203_model_34 | 0.7802396949685133 | 0.6841642505589037 | 0.39151056369512177 | 0.4561002108731322 | 0.20802740235851566 |
| 10 | GBM_grid_0_AutoML_20181113_120203_model_103 | 0.7806436573121974 | 0.755575279116592 | 0.3829778571154854 | 0.42974948528472356 | 0.18468462010248482 |
| 11 | GBM_grid_0_AutoML_20181113_120203_model_82 | 0.7810476196558815 | 1.0533137256206284 | 0.38483480654514796 | 0.5684054601211439 | 0.3230847670955293 |
| 12 | GBM_grid_0_AutoML_20181113_120203_model_39 | 0.7812208604238252 | 0.5278357305219928 | 0.39049107770127867 | 0.4166878846553893 | 0.17362879321858302 |
| 13 | GBM_grid_0_AutoML_20181113_120203_model_67 | 0.784371926373472 | 1.2699168097620763 | 0.4362458007076526 | 0.594085803801969 | 0.3529379422790316 |
| 14 | GBM_grid_0_AutoML_20181113_120203_model_220 | 0.7844294071812689 | 0.6286376740625584 | 0.4169801499610408 | 0.46553860864136315 | 0.2167261961357363 |
| 15 | GBM_grid_0_AutoML_20181113_120203_model_98 | 0.7865458185905706 | 0.6897316831381888 | 0.3930561587492176 | 0.4637718043169175 | 0.2150842864793692 |



😭 Model

| Model ID: GBM_grid_0_AutoML_20181113_120203_model_324 |
|------------------------------------------------------------------------------------------------------------------------------------------|
| Algorithm: Gradient Boosting Machine |
| Actions: 🗘 Refresh 🕴 Predict 🛓 Download POJO 🛓 Download Model Deployment Package (MOJO) 🖺 Export 💷 Inspect 🏦 Delete 🛓 Download Gen Model |
| MODEL PARAMETERS |
| SCORING HISTORY - LOGLOSS |
| ROC CURVE - TRAINING METRICS, AUC = 0.997559 |
| ROC CURVE - VALIDATION METRICS , AUC = 0.804742 |
| • VARIABLE IMPORTANCES |
| • TRAINING METRICS - CONFUSION MATRIX ROW LABELS: ACTUAL CLASS; COLUMN LABELS: PREDICTED CLASS |
| • VALIDATION METRICS - CONFUSION MATRIX ROW LABELS: ACTUAL CLASS; COLUMN LABELS: PREDICTED CLASS |
| • TRAINING METRICS - GAINS/LIFT TABLE |
| • VALIDATION METRICS - GAINS/LIFT TABLE |
| ▶ OUTPUT |
| ▶ OUTPUT - MODEL SUMMARY |
| • OUTPUT - SCORING HISTORY |
| • OUTPUT - TRAINING_METRICS |
| DOMAIN |
| • OUTPUT - TRAINING_METRICS - METRICS FOR THRESHOLDS (BINOMIAL METRICS AS A FUNCTION OF CLASSIFICATION THRESHOLDS) |
| • OUTPUT - TRAINING_METRICS - MAXIMUM METRICS (MAXIMUM METRICS AT THEIR RESPECTIVE THRESHOLDS) |

• OUTPUT - TRAINING_METRICS - GAINS/LIFT TABLE (AVG RESPONSE RATE: 52.87 %, AVG SCORE: 52.86 %)



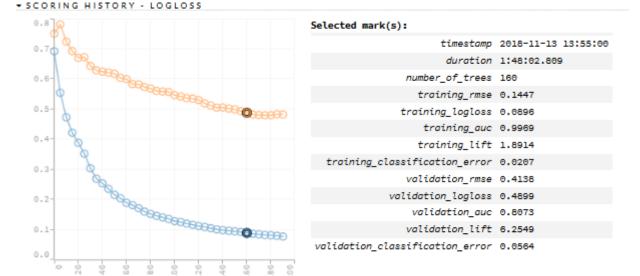
🕞 Model

Model ID: GBM_grid_0_AutoML_20181113_120203_model_324

Algorithm: Gradient Boosting Machine Actions: Refresh Predict... & Download POJO & Download Model Deployment Package (MOJO) Export Inspect Delete & Download Gen Model * MODEL PARAMETERS

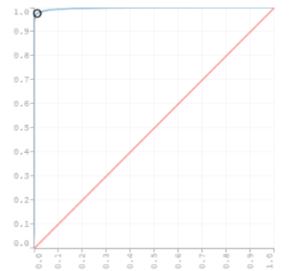
| Parameter | Value | Description |
|-----------------------------------|---------------------------------------------|----------------------------------------------------------------------------------------------------------------|
| model_id | GBM_grid_0_AutoML_20181113_120203_model_324 | Destination id for this model; auto-generated if not specified. |
| training_frame | _928dfd275f0bc66bf9d253e54f2a4f65 | Id of the training data frame. |
| validation_frame | automl_validation_Key_Frame_X_train.hex | Id of the validation data frame. |
| keep_cross_validation_predictions | true | Whether to keep the predictions of the cross-validation models. |
| score_tree_interval | 5 | Score the model after every so many trees. Disabled if set to 0. |
| response_column | out_of_cash | Response variable column. |
| ignored_columns | | Names of columns to ignore for training. |
| ntrees | 10000 | Number of trees. |
| min_rows | 1 | Fewest allowed (weighted) observations in a leaf. |
| stopping_rounds | 3 | Early stopping based on convergence of stopping_metric. Stop if simple moving average of events (0 to disable) |
| stopping_tolerance | 0.002851410881423444 | Relative tolerance for metric-based stopping criterion (stop if relative improvement is no |
| max_runtime_secs | 430 | Maximum allowed runtime in seconds for model training. Use 0 to disable. |
| seed | -5783679485009037000 | Seed for pseudo random number generator (if applicable) |
| distribution | bernoulli | Distribution function |
| sample_rate | 0.8 | Row sample rate per tree (from 0.0 to 1.0) |
| col_sample_rate | 0.7 | Column sample rate (from 0.0 to 1.0) |
| col_sample_rate_per_tree | 0.4 | Column sample rate per tree (from 0.0 to 1.0) |
| | | |





MyStats 2018

***** ROC CURVE - TRAINING METRICS , AUC = 0.997559



| Threshold: | Criterion: | |
|--------------------|------------|---|
| 0.4610064498097649 | ▼ max f1 | • |

| • | 1.0 | 1573 | 63454 | 6.8242 | 1573 / 65027 | - |
|-----------------------|------------------|-------|-------|--------|--------------|---|
| СМ | 0.0 | 57219 | 747 | | 747 / 57966 | - |
| | Actual/Predicted | 0.0 | 1.0 | Error | Rate | |
| idx | 195 | | | | | |
| | 0.9758 | | | | | |
| fpr | 0.0129 | | | | | |
| fnr | 0.0242 | | | | | |
| tnr | 0.9871 | | | | | |
| tps | 63454 | | | | | |
| fps | 747 | | | | | |
| fns | 1573 | | | | | |
| tns | 57219 | | | | | |
| on_per_class_accuracy | 0.9815 | | | | | = |
| in_per_class_accuracy | 0.9758 | | | | | |
| absolute_mcc | 0.9623 | | | | | |
| specificity | 0.9871 | | | | | |
| recall | | | | | | |
| precision | | | | | | |
| accuracy | | | | | | |
| f0point5 | | | | | | |
| | 0.9783 | | | | | |
| | 0.9820 | | | | | Â |
| threshold | 0 4610 | | | | | |



- ROC CURVE - VALIDATION METRICS , AUC = 0.804742

1.0

0.9

0.8-

0.7

0.6-

0.5-

0.4-

0.3-

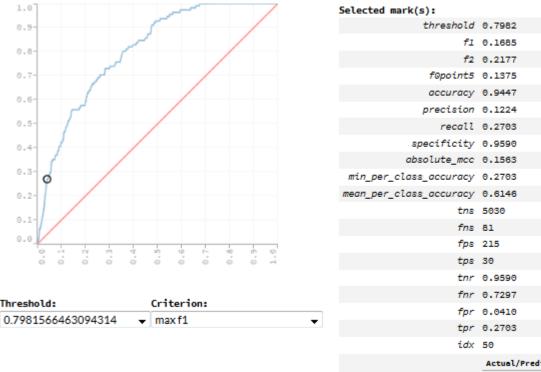
0.2-

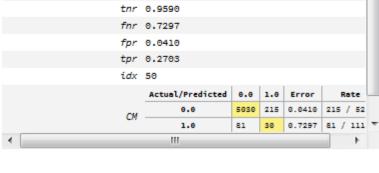
0.1-

0.0

Threshold:

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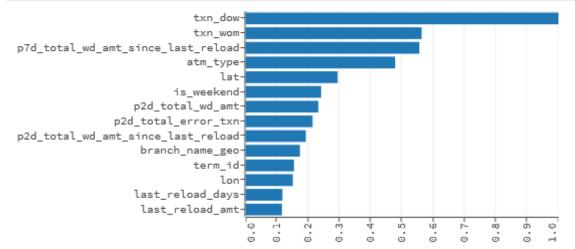


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Rate

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VARIABLE IMPORTANCES

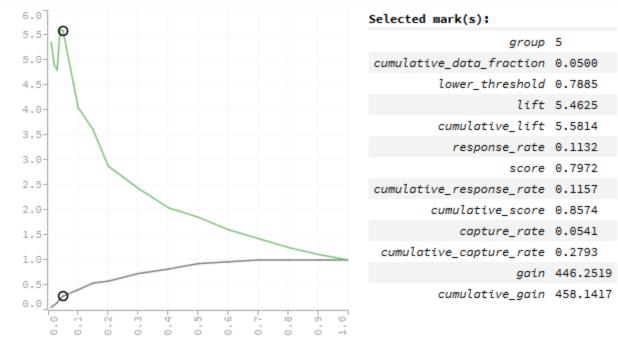




TRAINING METRICS - CONFUSION MATRIX ROW LABELS: ACTUAL CLASS; COLUMN LABELS: PREDICTED CLASS

| | 0.0 | 1.0 | Error | Rate | Recall | • |
|-----------|-------|-------|--------|--------------------|--------|---|
| 0.0 | 57219 | 747 | 0.0129 | 747 / 57,966 | 0.97 | |
| 1.0 | 1573 | 63454 | 0.0242 | 1,573 / 65,027 | 0.99 | Ε |
| Total | 58792 | 64201 | 0.0189 | 2,320 / 122,993 | | |
| Precision | 1 | | | P | | - |
| • | | | | | ۴ | |





VALIDATION METRICS - GAINS/LIFT TABLE



OUTPUT - SCORING HISTORY

| timestamp | duration | number_of_trees | training_rmse | training_logloss | training_auc | <pre>training_lift</pre> |
|------------------------|-------------|-----------------|---------------|------------------|--------------|--------------------------|
| 2018-11-13 13:54:54 | 1:47:57.111 | Θ | 0.4992 | 0.6915 | 0.5000 | 1.0 |
| 2018-11-13 13:54:55 | 1:47:57.253 | 5 | 0.4271 | 0.5541 | 0.9072 | 1.8914 |
| 2018-11-13 13:54:55 | 1:47:57.399 | 10 | 0.3837 | 0.4725 | 0.9217 | 1.8914 |
| 2018-11-13 13:54:55 | 1:47:57.548 | 15 | 0.3575 | 0.4214 | 0.9292 | 1.8914 |
| 2018-11-13 13:54:55 | 1:47:57.704 | 20 | 0.3411 | 0.3878 | 0.9369 | 1.8914 |
| 2018-11-13 13:54:55 | 1:47:57.862 | 25 | 0.3217 | 0.3519 | 0.9505 | 1.8914 |
| 2018-11-13 13:54:55 | 1:47:58.008 | 30 | 0.2923 | 0.3037 | 0.9700 | 1.8914 |
| 2018-11-13 13:54:55 | 1:47:58.160 | 35 | 0.2703 | 0.2688 | 0.9796 | 1.8914 |
| 2018-11-13 13:54:56 | 1:47:58.309 | 40 | 0.2617 | 0.2536 | 0.9816 | 1.8914 |
| 2018-11-13 13:54:56 | 1:47:58.461 | 45 | 0.2506 | 0.2355 | 0.9844 | 1.8914 |
| 2018-11-13 13:54:56 | 1:47:58.612 | 50 | 0.2379 | 0.2157 | 0.9871 | 1.8914 |
| 2018-11-13 13:54:56 | 1:47:58.795 | 55 | 0.2301 | 0.2040 | 0.9885 | 1.8914 |



References

- I. <u>https://ail00.stanford.edu/2016-report/appendix-i-short-history-ai</u>
- 2. <u>http://www.csis.pace.edu/~ctappert/dps/pdf/ai-chess-deep.pdf</u>
- 3. <u>https://skymind.ai/wiki/neural-network</u>
- 4. <u>https://medium.com/datathings/neural-networks-and-backpropagation-explained-in-a-simple-way-f540a3611f5e</u>
- 5. <u>http://ruder.io/optimizing-gradient-descent/</u>
- 6. <u>https://arxiv.org/pdf/1707.07012.pdf</u>

